

The seminar on differential geometry will continue with this lecture:

October 21, 10am, lecture room M5.

Jan Slovák:

Non-holonomic equations in geometric control theory

Abstract:

The talk will remind my earlier exposition of a new approach to building non-holonomic equations equivalent to the hamiltonian formalism. In particular, I will reveal how to rewrite them as "nice" holonomic equations and present some examples.