

Věta (Výpočet torze). Pro křivku při parametrické reprezentaci $x = x(t), y = y(t), z = z(t)$ v prostoru platí

$$\tau = \frac{\rho^2}{(x'^2 + y'^2 + z'^2)^3} \begin{vmatrix} x' & y' & z' \\ x'' & y'' & z'' \\ x''' & y''' & z''' \end{vmatrix}$$

Důkaz.

$$\mathbf{b} = \mathbf{t} \times \mathbf{n}$$

\mathbf{t} normovaný tečný vektor $\mathbf{t} = \dot{\mathbf{k}} = \begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{pmatrix}$

\mathbf{n} hlavní normála $\mathbf{n} = \frac{\ddot{\mathbf{k}}}{\|\ddot{\mathbf{k}}\|} = \frac{1}{\|\dot{\mathbf{k}}\|} \begin{pmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{pmatrix}$

k funkce délky oblouku s

Z toho vyplývá:

$$\mathbf{b} = \mathbf{t} \times \mathbf{n} = \frac{\dot{\mathbf{k}} \times \ddot{\mathbf{k}}}{\|\ddot{\mathbf{k}}\|} = \frac{1}{\|\dot{\mathbf{k}}\|} \left(\begin{vmatrix} \dot{y} & \dot{z} \\ \ddot{y} & \ddot{z} \end{vmatrix}, - \begin{vmatrix} \dot{x} & \dot{z} \\ \ddot{x} & \ddot{z} \end{vmatrix}, \begin{vmatrix} \dot{x} & \dot{y} \\ \ddot{x} & \ddot{y} \end{vmatrix} \right)^T$$

První souřadnice:

$$\frac{\begin{vmatrix} \dot{y} & \dot{z} \\ \ddot{y} & \ddot{z} \end{vmatrix}}{\|\ddot{\mathbf{k}}\|} = \frac{\dot{y}\ddot{z} - \dot{y}\ddot{z}}{\|\ddot{\mathbf{k}}\|} = \frac{\dot{y}\ddot{z} - \dot{y}\ddot{z}}{\sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}}$$

Derivace:

$$\begin{aligned} \dot{\mathbf{b}} &= \frac{(\dot{y}\ddot{z} + \dot{y}'\ddot{z}' - \dot{y}'\ddot{z} - \dot{y}\ddot{z}')\|\ddot{\mathbf{k}}\| - (\dot{y}\ddot{z} - \dot{y}\ddot{z}')2(\dot{x}\dot{x}' + \dot{y}\dot{y}' + \dot{z}\dot{z}')}{2\|\ddot{\mathbf{k}}\|(\dot{x}^2 + \dot{y}^2 + \dot{z}^2)} = \\ &= \frac{\begin{vmatrix} \dot{y} & \dot{y}' \\ \dot{z} & \dot{z}' \end{vmatrix}}{\|\ddot{\mathbf{k}}\|} - \frac{\begin{vmatrix} \dot{y} & \dot{y}' \\ \dot{z} & \dot{z}' \end{vmatrix}}{\|\ddot{\mathbf{k}}\|^3}(\dot{x}\dot{x}' + \dot{y}\dot{y}' + \dot{z}\dot{z}') = \frac{\dot{\mathbf{k}} \times \ddot{\mathbf{k}}}{\|\ddot{\mathbf{k}}\|} - \frac{\dot{\mathbf{k}} \times \ddot{\mathbf{k}}}{\|\ddot{\mathbf{k}}\|^3} \langle \ddot{\mathbf{k}}, \dot{\mathbf{k}} \rangle \end{aligned}$$

□