Two contributions from symbolic dynamics to the comprehension of Green's relations in relatively free profinite semigroups

#### Alfredo Costa, Centro de Matemática da Universidade de Coimbra

Joint work with Jorge Almeida, José Carlos Costa and Marc Zeitoun

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# Subshifts

A symbolic dynamical system of  $A^{\mathbb{Z}}$ , also called subshift, is a nonempty subset of  $\mathcal X$  such that

- $\mathcal{X}$  is topologically closed,
- $\sigma(\mathcal{X}) \subseteq \mathcal{X}$ ,
- $\sigma^{-1}(\mathcal{X}) \subseteq \mathcal{X}.$

$$\sigma((x_i)_{i\in\mathbb{Z}})=(x_{i+1})_{i\in\mathbb{Z}}, \qquad x_i\in A$$

 $L(\mathcal{X}) = \{ u \in A^+ : u = x_i x_{i+1} \dots x_{i+n} \text{ for some } x \in \mathcal{X}, i \in \mathbb{Z}, n \ge 0 \}.$ 

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## Factorial, prolongable and irreducible sets



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Let S be a semigroup. A subset K of S is...

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#### Proposition

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A subshift is irreducible if  $L(\mathcal{X})$  is irreducible.

Free profinite semigroups and symbolic dynamics

#### From hereon V contains $\mathscr{L}SI$ .

- $\overline{L(\mathcal{X})}$ : the topological closure of  $L(\mathcal{X})$  in  $\overline{\Omega}_A V$
- $\mathcal{M}(\mathcal{X})$ : the set of elements of  $\overline{\Omega}_A V$  whose finite factors belong to  $L(\mathcal{X})$ .

• One has 
$$L(\mathcal{X}) \subseteq \mathcal{M}(\mathcal{X}).$$

■ In general, the equality does not hold.

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# The $\mathcal{J}$ -classes $\mathcal{J}(\mathcal{X})$ and $\mathcal{J}\mathcal{M}(\mathcal{X})$

If K is a closed, factorial, prolongable, irreducible subset of the compact semigroup S, then K has a minimum  $\mathcal{J}$ -class. This  $\mathcal{J}$ -class is regular.

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• The sets  $\mathcal{M}(\mathcal{X})$  and  $\overline{\mathcal{L}(\mathcal{X})}$  are prolongable and irreducible.

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- $\mathcal{J}(\mathcal{X})$ : the minimal  $\mathcal{J}$ -class of  $\overline{L(\mathcal{X})}$ .
- $\mathcal{JM}(\mathcal{X})$ : the minimal  $\mathcal{J}$ -class of  $\mathcal{M}(\mathcal{X})$ .

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### The minimal case

A subshift is minimal if it does not contain proper subshifts.

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Example For the Fibonacci substitution  $\varphi(a) = ab, \quad \varphi(b) = a,$ the set of factors of the words  $\varphi^n(a)$  defines a minimal subshift.

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#### Theorem (Almeida, 2003)

If  $\mathcal{X}$  is a minimal subshift, then  $\mathcal{J}(\mathcal{X}) = \mathcal{JM}(\mathcal{X})$  is a maximal regular  $\mathcal{J}$ -class. All maximal regular  $\mathcal{J}$ -classes are of this form.

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### Chains of regular $\mathcal{R}$ -classes

Suppose |A| > 1.

Theorem (J. C. Costa, 2001)

There is a  $<_{\mathscr{R}}$ -chain of  $2^{\aleph_0}$  elements of  $\overline{\Omega}_A V$ .

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 $\mathcal{X} \subseteq \mathcal{Y} \Leftrightarrow L(\mathcal{X}) \subseteq L(\mathcal{Y})$ 

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There is a chain (for inclusion) with  $2^{\aleph_0}$  irreducible subshifts of  $A^{\mathbb{Z}}$ .

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#### Corollary

There is a  $<_{\mathscr{J}}$ -chain of  $2^{\aleph_0}$  regular elements of  $\overline{\Omega}_A V$ .

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There is a  $<_{\mathscr{J}}$ -chain of  $2^{\aleph_0}$  regular elements of  $\overline{\Omega}_A V$ .

Theorem (First contribution. In a work with J. Almeida, J. C. Costa and M. Zeitoun)

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# Chains of regular $\mathcal{R}$ -classes

Let  $\mathscr{C}$  be a chain of irreducible subshifts of  $A^{\mathbb{Z}}$ .

Subshifts

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# Chains of regular $\mathcal{R}$ -classes

Let  $\mathscr{C}$  be a chain of irreducible subshifts of  $A^{\mathbb{Z}}$ . Let f be a function  $\text{Dom} f \subseteq \mathscr{C} \to \overline{\Omega}_A V$  such that

• 
$$f(\mathcal{X}) \in \mathcal{JM}(\mathcal{X})$$

 $\blacksquare \ \mathcal{X} \supseteq \mathcal{Y} \Leftrightarrow f(\mathcal{X}) <_{\mathscr{R}} f(\mathcal{Y}) \qquad (\mathcal{X}, \mathcal{Y} \in \mathrm{Dom} f)$ 

SUBSHIFTS

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For every  $u, v \in \mathcal{JM}(\mathcal{X})$  there is  $w \in \overline{\Omega}_A V$ , depending only on the finite suffixes of u and on the finite prefixes of v, such that  $uwv \in \mathcal{JM}(\mathcal{X})$ . Subshifts

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Suppose  $\text{Dom} f \neq \mathscr{C}$ . Let  $\mathcal{Z} \in \mathscr{C} \setminus \text{Dom} f$  and  $v \in \mathcal{JM}(\mathcal{Z})$ . Let u be an accumulation point of  $(f(\mathcal{X}))_{\mathcal{X} \subseteq \mathcal{Z}}$ .

$$f': \mathcal{X} \in \text{Dom} f \cup \{\mathcal{Z}\} \mapsto \begin{cases} f(\mathcal{X}) & \text{if } \mathcal{X} \subsetneq \mathcal{Z}, \\ uwv & \text{if } \mathcal{X} = \mathcal{Z}, \\ uwvw'f(\mathcal{X}) & \text{if } \mathcal{Z} \subsetneq \mathcal{X}, \end{cases}$$

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## Chains of regular $\mathcal{R}$ -classes

Theorem (First contribution. In a work with J. Almeida, J. C. Costa and M. Zeitoun) Suppose |A| > 1. There is a  $<_{\mathscr{R}}$ -chain of  $2^{\aleph_0}$  regular elements of  $\overline{\Omega}_A \vee$ , with a minimum at the minimal ideal, and with a subsequence converging to this minimum.

The proof uses the upper semi-continuity of the *entropy of pseudowords*, another concept borrowed from symbolic dynamics by Almeida and Volkov (2006).

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### Rees matrix representation

A regular  $\mathcal{J}$ -class of a compact semigroup is isomorphic to a *Rees* matrix partial compact semigroup  $\mathcal{M}(I, G, \Lambda; P) = I \times G \times \Lambda$ , where

- I and Λ are compact spaces;
- *G* is a compact group;
- P is a continuous partial function  $\Lambda \times I \rightarrow G$ ;
- $(i_1, g_1, \lambda_1)(i_2, g_2, \lambda_2) = (i_1, g_1 P(\lambda_1, i_2)g_2, \lambda_2).$

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### Right and left rays

We say that a right infinite sequence

 $x_0 x_1 x_2 x_3 \cdots$ 

of elements of A is a right ray. If

 $x = \cdots x_{-3} x_{-2} x_{-1} x_0 x_1 x_2 x_3 \cdots$ 

then  $x_0x_1x_2\cdots$  is a right ray of x and we use the notation

 $\overrightarrow{x} = x_0 x_1 x_2 x_3 \cdots$ 

Dually, one defines *left ray* and  $\overleftarrow{x}$ .

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# Right and left rays of a pseudoword

Let *u* be an infinite pseudoword.

Let

 $u_0 u_1 \cdots u_{n-2} u_{n-1}$ 

be the prefix of length n of u.

Definition

Right ray defined by u:

$$\overrightarrow{u} = u_0 u_1 u_2 \cdots u_{n-2} u_{n-1} u_n u_{n+1} \cdots$$

### Right and left rays of $\mathcal{X}$

#### Definition

$$\dot{\mathcal{X}} = \{ \overrightarrow{x} : x \in \mathcal{X} \}$$
$$\dot{\overleftarrow{\mathcal{X}}} = \{ \overleftarrow{x} : x \in \mathcal{X} \}$$

 $z \in \overrightarrow{\mathcal{X}} \iff \exists y \in A^{\mathbb{Z}^-} : y.z \in \mathcal{X}$ 

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A parametrization of  $\mathcal{R}$ -classes and  $\mathcal{L}$ -classes

#### Let $\mathcal{X}$ be a minimal subshift and $u, v \in \mathcal{J}(\mathcal{X})$ .

#### Lemma

• 
$$u \mathcal{R} v$$
 if and only if  $\overrightarrow{u} = \overrightarrow{v}$ 

• 
$$u \mathcal{L} v$$
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#### Corollary

 $u \mathcal{H} v$  if and only if  $\overleftarrow{u} . \overrightarrow{u} = \overleftarrow{v} . \overrightarrow{v}$ .

# A closed coordinate system

### Let $\mathcal{X}$ be a minimal subshift.

Let G be a maximal subgroup of  $\mathcal{J}(\mathcal{X})$  with idempotent e.

There are families

$$(l_y)_{y\in \overleftarrow{\mathcal{X}}} (r_z)_{z\in \overrightarrow{\mathcal{X}}}$$

such that

*I<sub>y</sub> R e* and *I<sub>y</sub>* is in the *L*-class determined by *y*; *r<sub>z</sub> R e* and *r<sub>z</sub>* is in the *R*-class determined by *z*; *I<sub>y</sub>* ∈ *G* ⇒ *I<sub>y</sub>* = *e*, *r<sub>z</sub>* ∈ *G* ⇒ *r<sub>z</sub>* = *e*;

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the sets {*l<sub>y</sub>* : *y* ∈ *X*} and {*r<sub>z</sub>* : *z* ∈ *X*} are closed;

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such that

- $l_y \mathcal{R}$  e and  $l_y$  is in the  $\mathcal{L}$ -class determined by y;
- $r_z \mathcal{R} e$  and  $r_z$  is in the  $\mathcal{R}$ -class determined by z;

$$\bullet \ l_y \in G \Rightarrow l_y = e, \quad r_z \in G \Rightarrow r_z = e;$$

- the sets  $\{l_y : y \in \overleftarrow{\mathcal{X}}\}$  and  $\{r_z : z \in \overrightarrow{\mathcal{X}}\}$  are closed;
- the maps  $y \mapsto l_y$  and  $z \mapsto r_z$  are continuous.

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## Rees matrix representation of $\mathcal{J}(\mathcal{X})$

#### Let $\mathcal{X}$ be a minimal subshift.

Ρ

$$\begin{array}{rcccc} : \overleftarrow{\mathcal{X}} \times \overrightarrow{\mathcal{X}} & \to & \mathcal{G} \\ & & (y,z) & \mapsto & \begin{cases} l_y r_z & \text{ if } y.z \in \mathcal{X} \\ \text{ not defined } & \text{ if } y.z \notin \mathcal{X} \end{cases} \end{array}$$

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Second contribution. With J. Almeida.

$$\mathscr{M}(\overrightarrow{\mathcal{X}}, \mathcal{G}, \overleftarrow{\mathcal{X}}; P) \rightarrow \mathcal{J}(\mathcal{X})$$
  
 $(z, g, y) \mapsto r_z g l_y.$ 

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## The Sturmian case

If  $\mathcal X$  is a Sturmian subshift of  $\{a,b\}^{\mathbb Z}$ , then there are  $x,y\in\mathcal X$  such that

- $x = \cdots x_{-4} x_{-3} x_{-2} a.b x_1 x_2 x_3 \cdots;$
- $y = \cdots x_{-4}x_{-3}x_{-2}b_{\cdot a}x_{1}x_{2}x_{3}\cdots;$
- if  $z, w \in \mathcal{X}$  have a common (right or left) ray, then z = w or  $\{z, w\} = \{\sigma^n(x), \sigma^n(y)\}$  for some  $n \in \mathbb{Z}$ .

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• if  $z, w \in \mathcal{X}$  have a common (right or left) ray, then z = w or  $\{z, w\} = \{\sigma^n(x), \sigma^n(y)\}$  for some  $n \in \mathbb{Z}$ .

Given  $z \in \mathcal{X}$ , the right ray

 $z_n z_{n+1} z_{n+2} z_{n+3} \cdots$ 

and the left ray

 $\cdots Z_{m-3}Z_{m-2}Z_{m-1}Z_m$ 

are respectively denoted by  $z_{[n]}$  and  $z_{m]}$ .



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# The Rauzy graph $\Sigma_n(\mathcal{X})$

- The edges are the words in  $L(\mathcal{X})$  with length n + 1.
- The vertices are the words in  $L(\mathcal{X})$  with length n.
- The edge  $a_1 a_2 \ldots a_{n-1} a_n$  has origin in  $a_1 a_2 \ldots a_{n-1}$  and terminus in  $a_2 \ldots a_{n-1} a_n$ .

# The centrally labeled Rauzy graph $\Sigma_{2n}(\mathcal{X})$

We assign to each edge of  $\sum_{2n}(\mathcal{X})$  its middle letter. This defines a nondeterministic automaton over the alphabet A with transitions

$$a_1a_2\ldots a_{2n} \xrightarrow{a_{n+1}} a_2\ldots a_{2n}a_{2n+1}$$

defined precisely when  $a_1a_2 \ldots a_{2n}a_{2n+1}$  belongs to  $L(\mathcal{X})$ .

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# A crucial property

Two paths labeled  $u = u_1 u_2$ , with  $|u_1| = |u_2| = n$ .



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# The transition semigroup of $\Sigma_{2n}(\mathcal{X})$ .

- The transition homomorphism of  $\sum_{2n}(\mathcal{X})$  is denoted by  $\eta_n$ .
- The transition semigroup of  $\Sigma_{2n}(\mathcal{X})$  is denoted by  $T_n(\mathcal{X})$ .

If  $\mathcal{X}$  is irreducible then  $\Sigma_{2n}(\mathcal{X})$  is strongly connected and  $\mathcal{T}_n(\mathcal{X})$  has a 0-minimum  $\mathcal{J}$ -class, denoted  $\mathcal{J}_n(\mathcal{X})$ .

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# A homomorphism of partial semigroups

Let  $m \geq 2n$ .

$$\psi_{m,n}: T_m(\mathcal{X}) \setminus \{0\} \quad \to \quad T_n(\mathcal{X}) \setminus \{0\}$$
$$\eta_m(u) \quad \mapsto \quad \eta_n(u)$$

Let 
$$s_1, s_2 \in \mathcal{T}_m(\mathcal{X})$$
.  
If  $s_1s_2 \neq 0$  then  $\psi_{m,n}(s_1)\psi_{m,n}(s_2) \neq 0$  and  
 $\psi_{m,n}(s_1s_2) = \psi_{m,n}(s_1)\psi_{m,n}(s_2)$ .

#### Lemma

If  $m \geq 2n$  then  $\psi_{m,n}(\mathcal{J}_m(\mathcal{X})) = \mathcal{J}_n(\mathcal{X})$ .

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### A projective limit of partial semigroups

- $\blacksquare n \preceq m \Leftrightarrow 2n \le m.$
- A directed system:

$$\mathscr{J}(\mathcal{X}) = \{\psi_{m,n} : \mathcal{J}_m(\mathcal{X}) \to \mathcal{J}_n(\mathcal{X}) \mid n, m \in \mathbb{Z}^+, n \leq m\}$$

For  $u \in \mathcal{M}(\mathcal{X})$ , let  $\theta_n(u)$  be an element of  $A^*$  such that  $i_{2n}(u) \cdot w \cdot t_{2n}(u) \in L(\mathcal{X})$ .

A well-defined continuous function:

$$\psi: \mathcal{JM}(\mathcal{X}) \rightarrow \varprojlim \mathscr{J}(\mathcal{X})$$
  
 $u \mapsto \left(\eta_n (i_{2n}(u) \cdot \theta_n(u) \cdot t_{2n}(u))\right)_n$ 

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# Second contribution revisited

#### Theorem

- The mapping  $\psi : \mathcal{JM}(\mathcal{X}) \to \varprojlim \mathcal{J}(\mathcal{X})$  is an onto homomorphism of partial semigroups.
- A pair (u, v) of elements of  $\mathcal{JM}(\mathcal{X})$  belongs to the kernel of  $\psi$  if and only if  $\overleftarrow{u} \cdot \overrightarrow{u} = \overleftarrow{v} \cdot \overrightarrow{v}$ .

#### Corollary

Suppose  $V \subseteq A$ . If  $\mathcal{X}$  is a minimal subshift then  $\psi : \mathcal{JM}(\mathcal{X}) \to \varprojlim \mathscr{J}(\mathcal{X})$  is a continuous isomorphism of compact partial semigroups.



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### Which idempotents are not lost?

#### Lemma

Let s be an element of  $\mathcal{J}_n(\mathcal{X})$ . Let  $m \geq 2n$ .

Then  $s = \psi_n(e)$  for some idempotent e of  $\mathcal{JM}(\mathcal{X})$  if and only if  $s = \psi_{m,n}(t)$  for some idempotent t of  $\mathcal{J}_m(\mathcal{X})$ .

