

Model dravec – kořist se vzájemnou interferencí dravce

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evropský
sociální
fond v ČR



EVROPSKÁ UNIE



MINISTERSTVO ŠKOLSTVÍ,
MLÁDEŽE A TĚLOVÝCHOVY



OP Vzdělávání
pro konkurenční
schopnost



A MathNet
sít pro transfer znalostí v aplikované matematice

INVESTICE DO ROZVOJE VZDĚLÁVÁNÍ

Model dravec – kořist

$$\begin{aligned}\frac{dN}{dt} &= rN \left(1 - \frac{N}{K}\right) - Pf(N, P), \\ \frac{dP}{dt} &= ePf(N, P) - mP,\end{aligned}$$

N, P ... populace kořisti a dravce

$f(N, P)$... funkční odpověď predátora

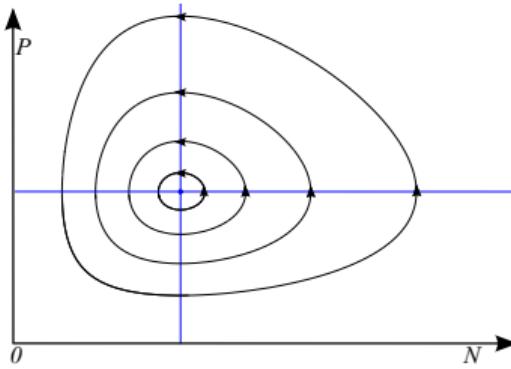
r, K, e, m ... parametry

Dynamika modelu

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Lotkův – Volterrův model: $K \rightarrow \infty, f(N, P) = aN$

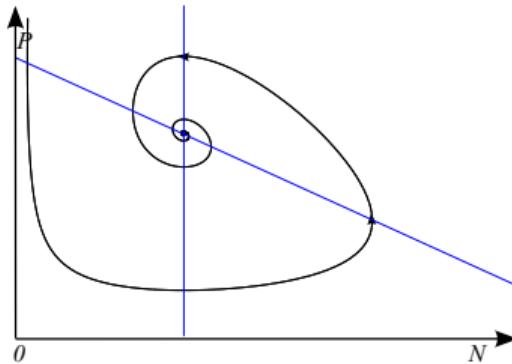
$$\begin{aligned}\frac{dN}{dt} &= rN \left(1 - \frac{N}{K}\right) - Pf(N, P), \\ \frac{dP}{dt} &= ePf(N, P) - mP,\end{aligned}$$



Dynamika modelu

Model s logistickým růstem kořisti: $K < \infty$, $f(N, P) = aN$

$$\begin{aligned}\frac{dN}{dt} &= rN \left(1 - \frac{N}{K}\right) - Pf(N, P), \\ \frac{dP}{dt} &= ePf(N, P) - mP,\end{aligned}$$



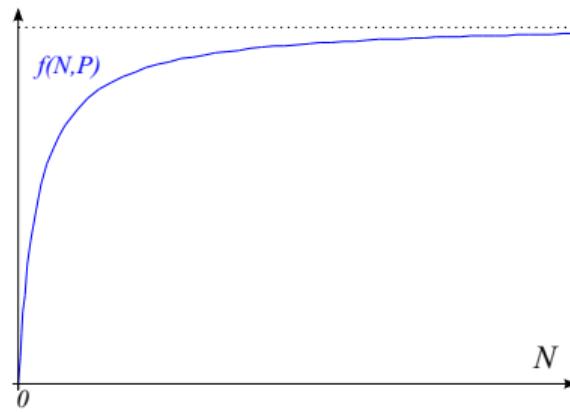
Rosenzweigův – MacArthurův model

$$\begin{aligned}\frac{dN}{dt} &= rN \left(1 - \frac{N}{K}\right) - Pf(N, P), \\ \frac{dP}{dt} &= ePf(N, P) - mP,\end{aligned}$$

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$$f(N, P) = \frac{\lambda N}{1 + h\lambda N},$$



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λ ... efektivita, s jakou dravec loví kořist

h ... čas, který je třeba na ulovení a zpracování kořisti.

Dynamika Rosenzweigova – MacArthurova modelu

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Rovnovážné body:

$[0, 0]$ sedlo

$[K, 0]$ stabilní rovnováha pro $e \leq hm$

stabilní rovnováha pro $e > hm$ a $K < \frac{m}{\lambda(e-mh)}$

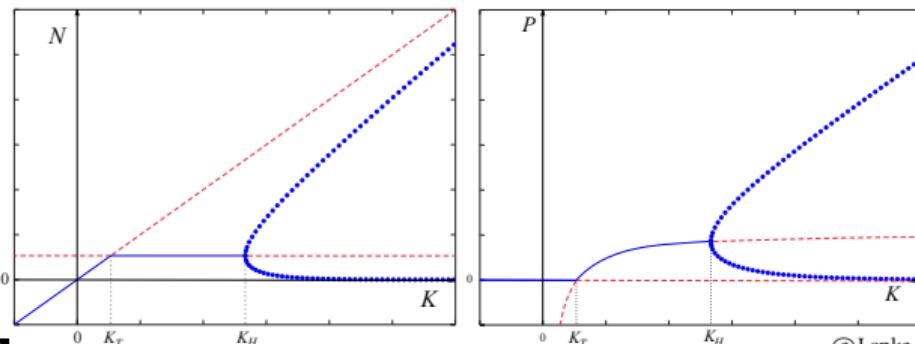
sedlo pro $e > hm$ a $K > \frac{m}{\lambda(e-mh)}$

$[N^*, P^*]$ další rovnováha pro $e > hm$

Dynamika Rosenzweigova – MacArthurova modelu

Rovnovážné body:

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sedlo pro $e > hm$ a $K > \frac{m}{\lambda(e-mh)}$
- [N^*, P^*] další rovnováha pro $e > hm$



Model se vzájemnou interferencí dravce

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Speciální tvar funkční odpovědi:

$$\lambda(P) = \frac{\lambda_0}{(b+P)^w}, \quad \text{kde } w > 0$$

Pro $w = 0$ jde o Rosenzweigův – MacArthurův model.

Rovnovážné body

Rovnovážné body

[0,0] sedlo

Rovnovážné body

$[0, 0]$ sedlo

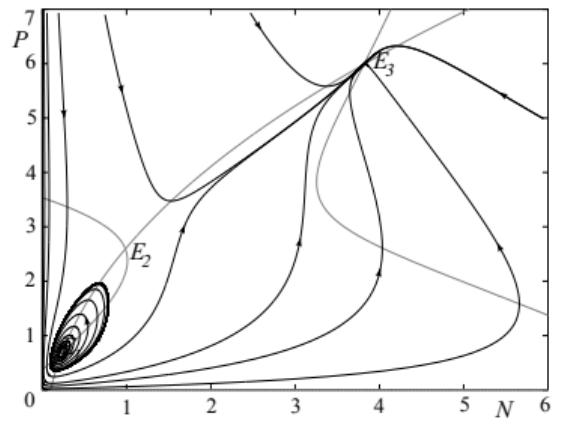
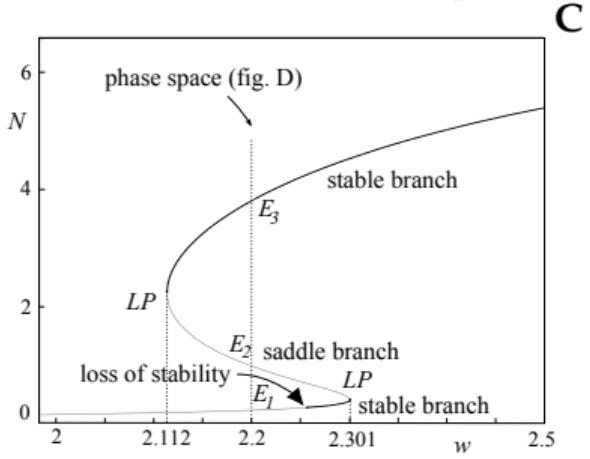
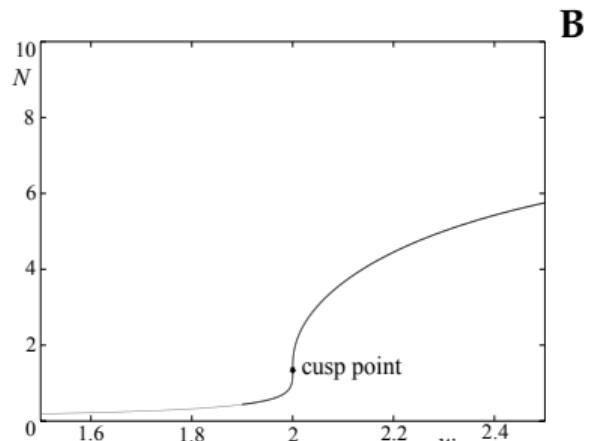
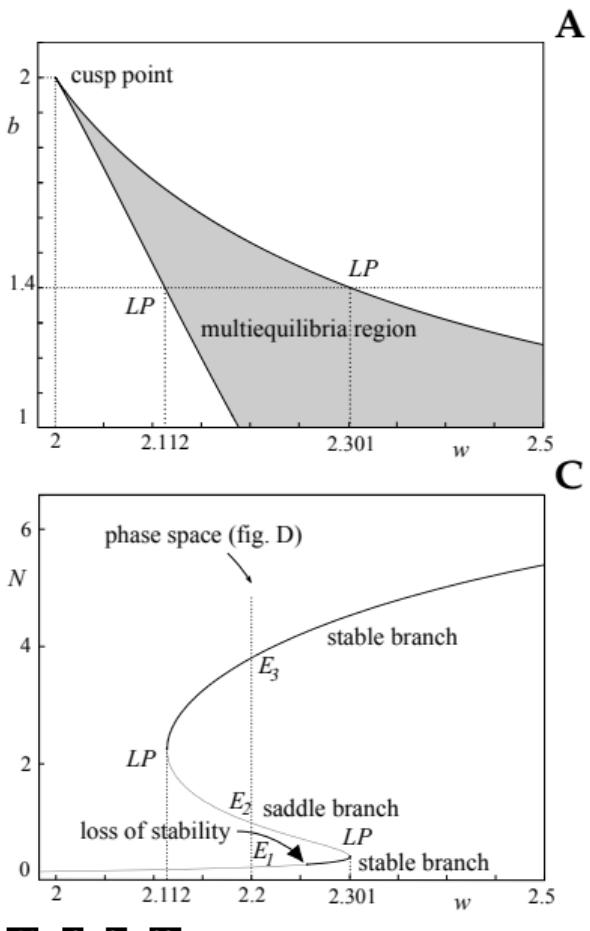
$[K, 0]$ stabilní rovnováha pro $e < hm$

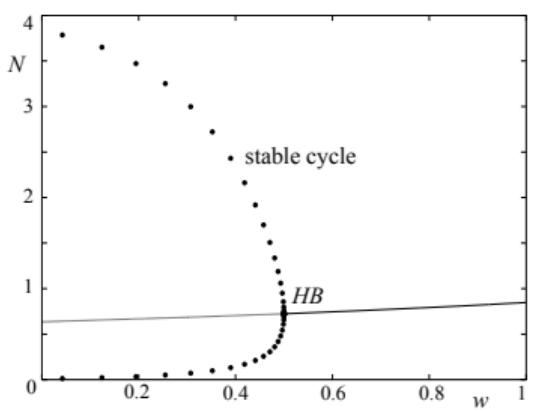
stabilní rovnováha pro $e > hm$ a $K < \frac{m}{\lambda(0)(e-mh)}$

sedlo pro $e > hm$ a $K > \frac{m}{\lambda(0)(e-mh)}$

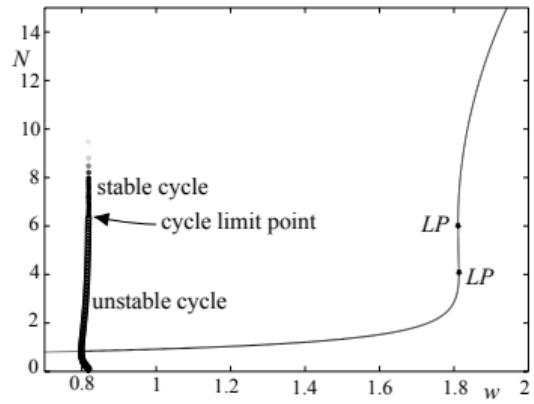
Rovnovážné body

- | | |
|-------------------|--|
| [0, 0] | sedlo |
| [K, 0] | stabilní rovnováha pro $e < hm$ |
| | stabilní rovnováha pro $e > hm$ a $K < \frac{m}{\lambda(0)(e-mh)}$ |
| | sedlo pro $e > hm$ a $K > \frac{m}{\lambda(0)(e-mh)}$ |
| [N^* , P^*] | další rovnováha(y) pro $e > hm$ |



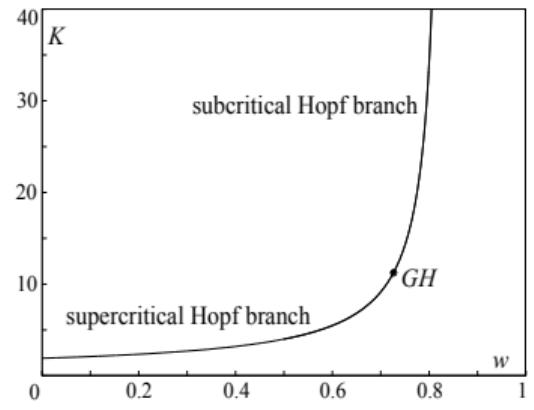
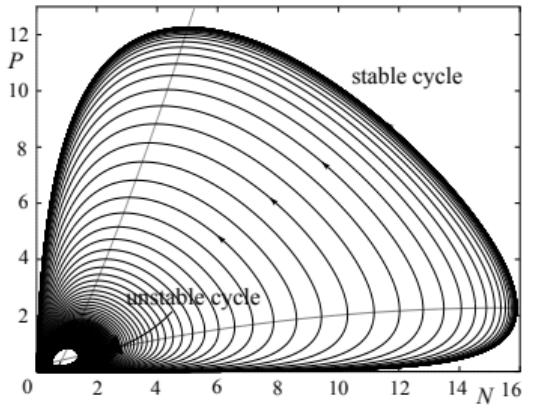


A

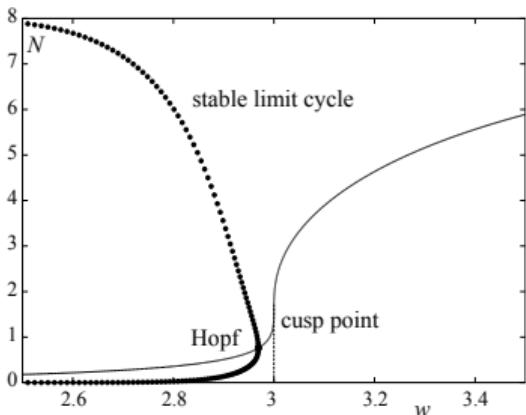
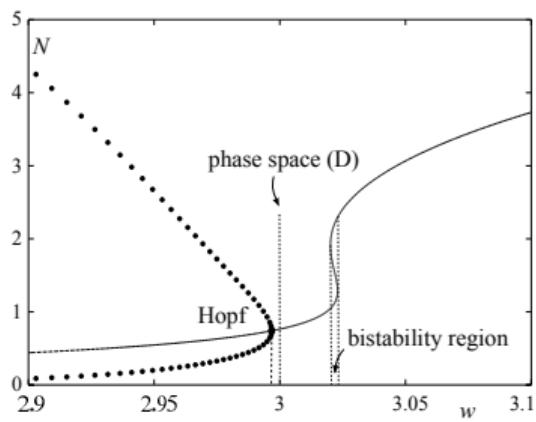
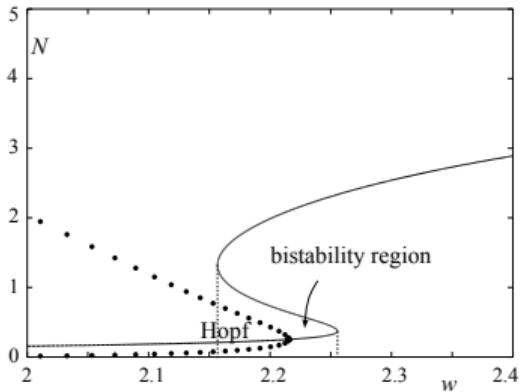
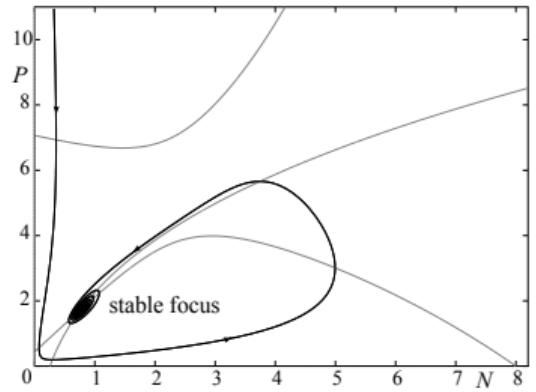


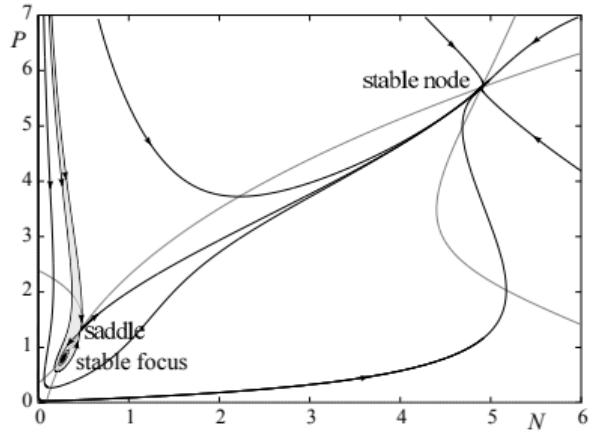
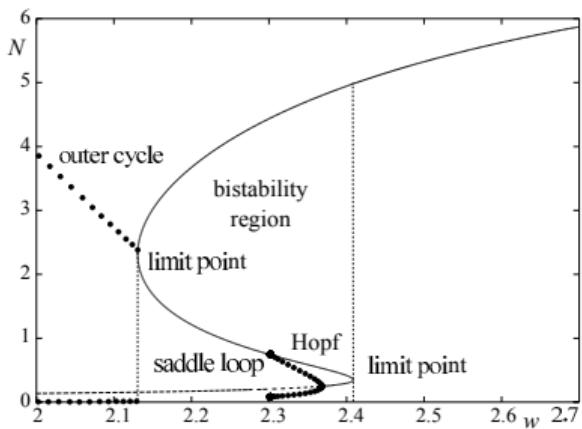
B

C

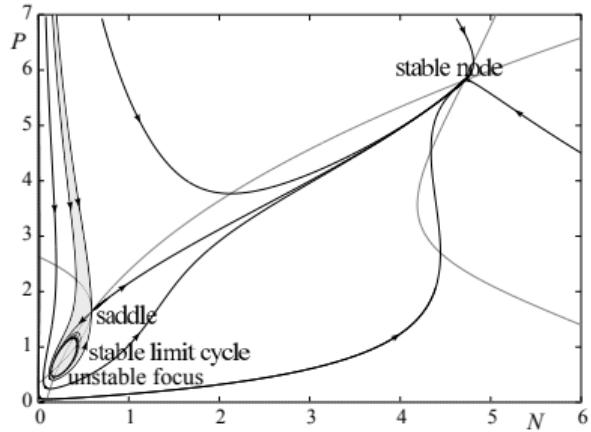
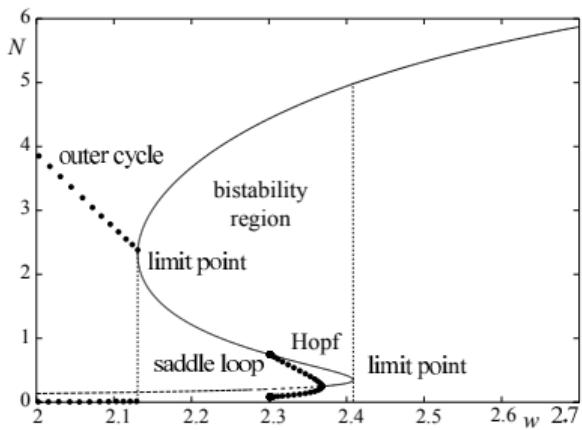


D

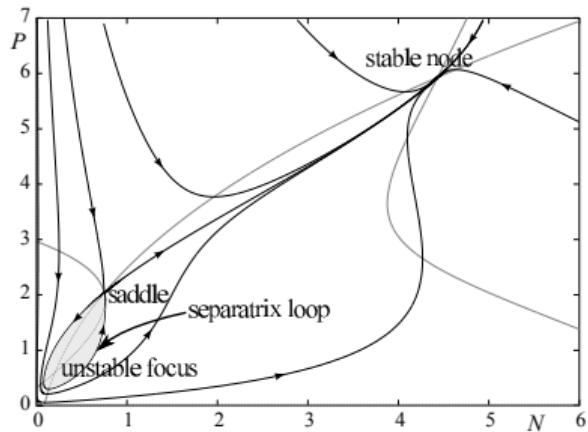
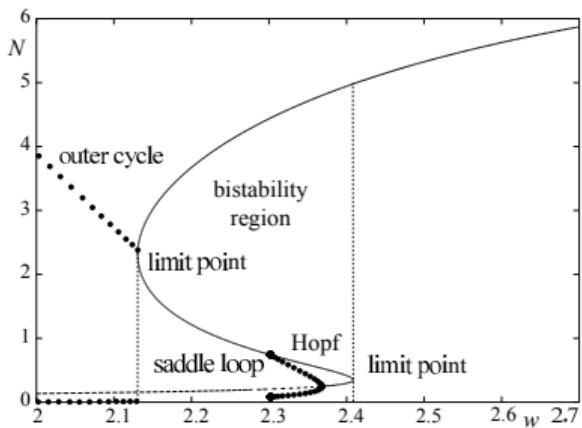

A

B

C

D



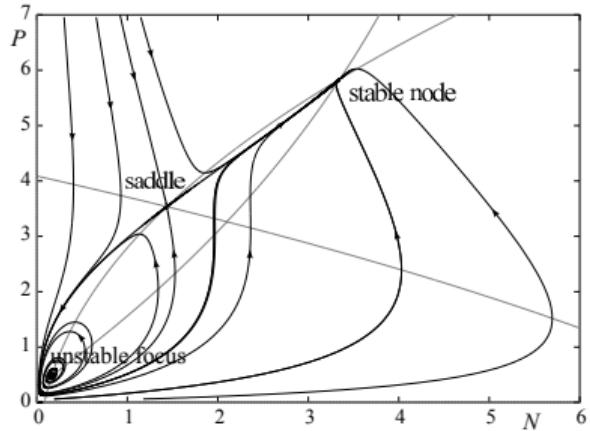
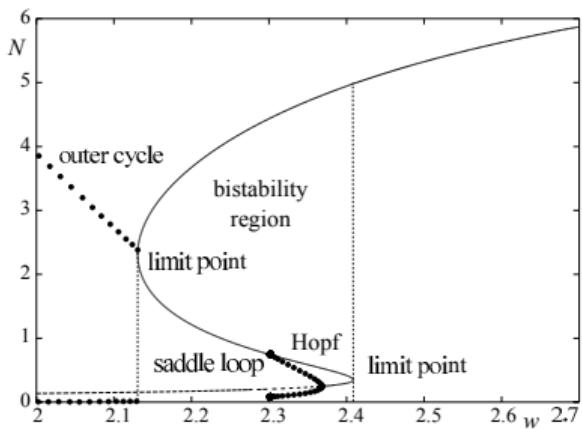
$$w = 2.39$$



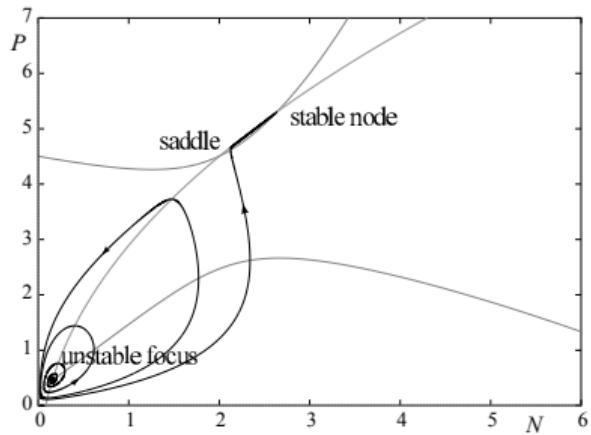
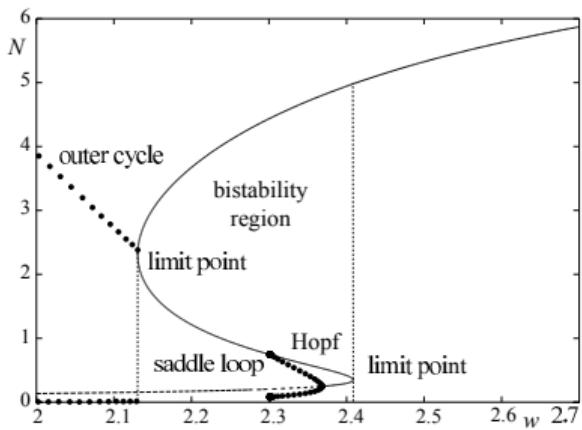
$$w = 2.35$$



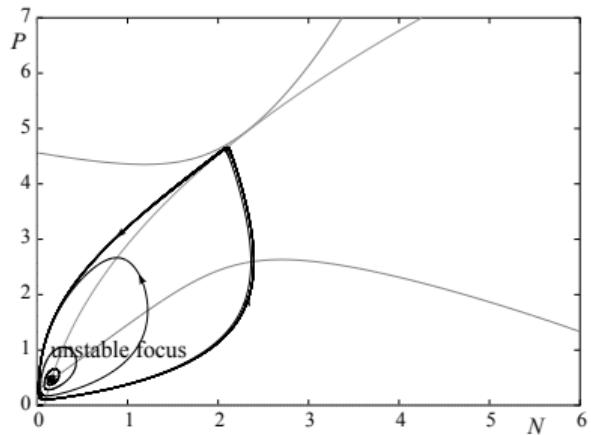
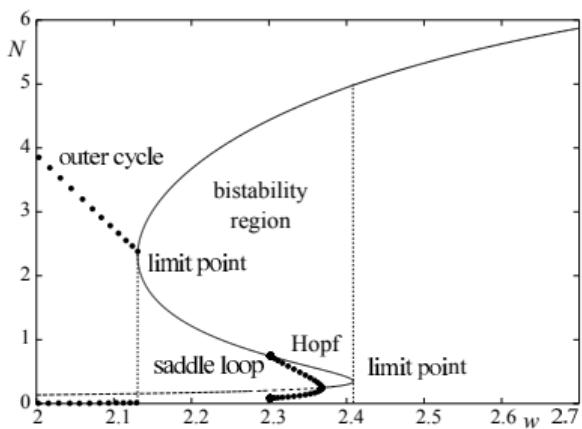
$$w = 2.3$$



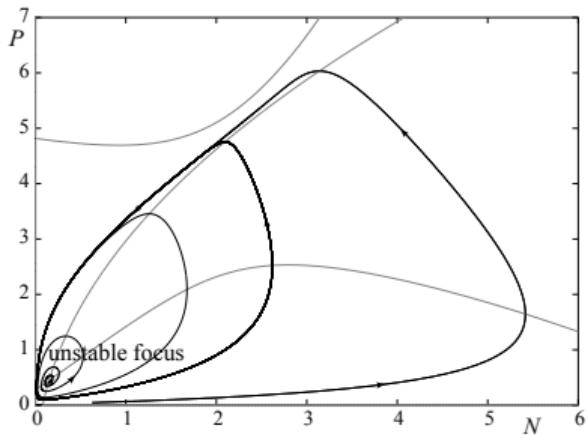
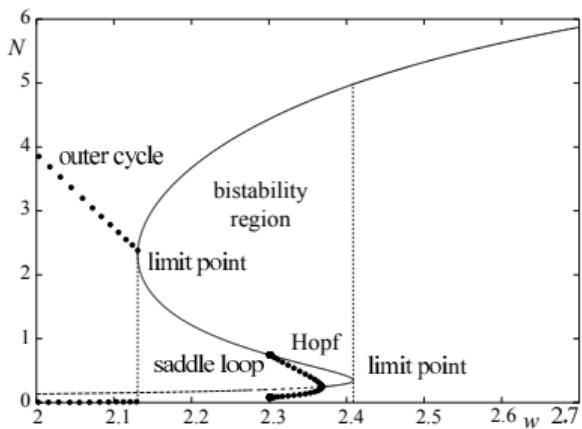
$$w = 2.1716$$



$$w = 2.135$$



$$w = 2.13$$



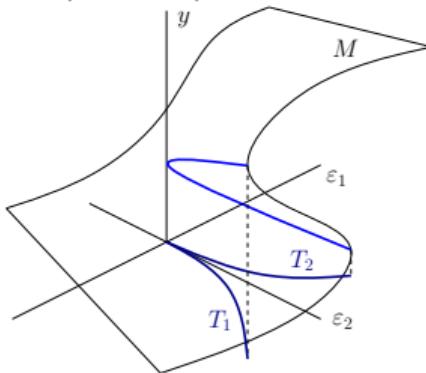
$$w = 2.11$$

Fold a cusp bifurkace

Nutná a postačující podmínka fold bifurkace rovnovážného bodu $[N^*, P^*]$ je:

$$\lambda^3(P^*) - C_1(2C_2 - \lambda(P^*))\lambda'(P^*) = 0,$$

kde $C_1 = \frac{er}{e - hm}$, $C_2 = \frac{m}{K(e - hm)}$.



$$\dot{y} = \varepsilon_1 + \varepsilon_2 y \pm y^3$$

Fold a cusp bifurkace

Pro

$$\lambda(P) = \frac{\lambda_0}{(b+P)^w}, \quad \text{kde } w > 0$$

podmínka přejde na

$$b\Lambda^2 + C_1(1-w)\Lambda + C_1C_2(2w-1) = 0,$$

$$\text{kde } \Lambda = \lambda(P^*), \quad C_1 = \frac{er}{e-hm}, \quad C_2 = \frac{m}{K(e-hm)}.$$

Fold a cusp bifurkace

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$$\lambda(P) = \frac{\lambda_0}{(b+P)^w}, \quad \text{kde } w > 0$$

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Odtud fold, resp. hystereze jen pro $w > 1$.

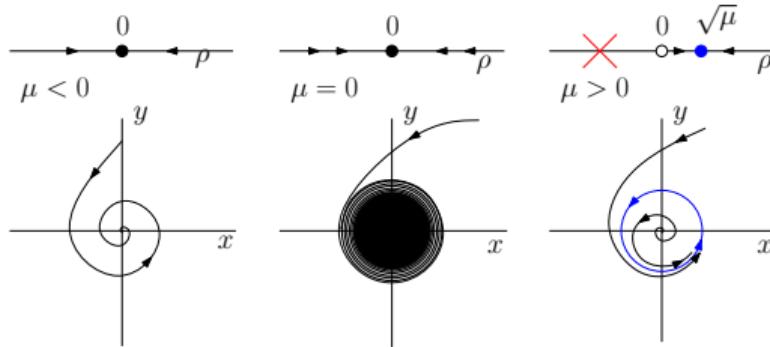
Kritická hodnota $w = w_c$ cusp bifurkace splňuje podmínu

$$(1-w_c)^2 = \frac{4bC_2}{C_1}(2w_c-1).$$

Hopfova bifurkace

Nutnou podmínkou vzniku Hopfovy bifurkace rovnovážného bodu $[N^*, P^*]$ je:

$$\lambda'(P^*) = \frac{(e + hm - \lambda(P^*)Kh(e - hm))\lambda^2(P^*)}{e(\lambda(P^*)K(e - hm) - m)},$$



$$\dot{\rho} = \rho(\mu - \rho^2)$$

Hopfova bifurkace

Pro

$$\lambda(P) = \frac{\lambda_0}{(b+P)^w}, \quad \text{kde } w > 0$$

podmínka přejde na

$$A\Lambda^3 + B\Lambda^2 + C\Lambda + D = 0,$$

kde

$$\Lambda = \lambda(P^*),$$

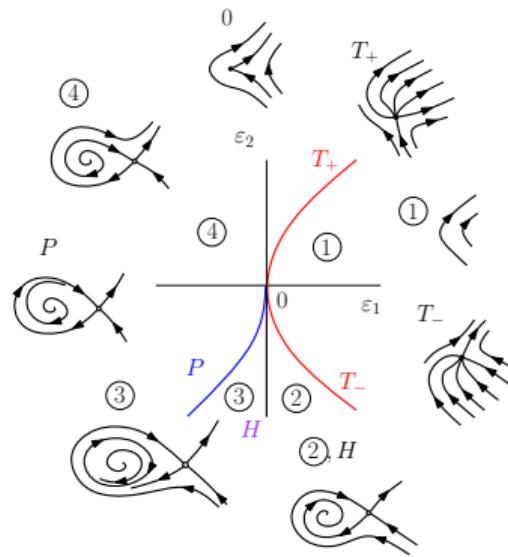
$$A = K^2hb(e - hm)^3 > 0,$$

$$B = K(e - hm)^2(hKer - b(e + hm) - wKe(e - hm)),$$

$$C = Ke(e - hm)(wm(e - hm) - r(2hm + e)),$$

$$D = emr(e + hm) > 0.$$

Bogdanova-Takensova bifurkace



$$\dot{y}_1 = y_2$$

$$\dot{y}_2 = \varepsilon_1 + \varepsilon_2 y_1 + y_1^2 + s y_1 y_2$$

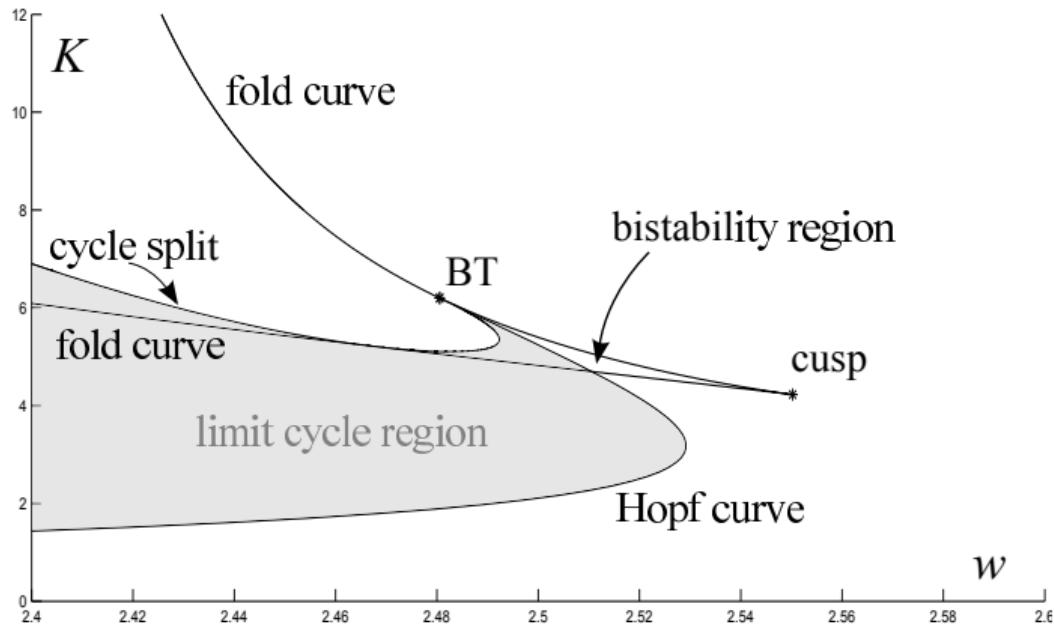
Bogdanova-Takensova bifurkace

$$\begin{aligned} b\Lambda^2 + C_1(1-w)\Lambda + C_1C_2(2w-1) &= 0, \\ A\Lambda^2 + B\Lambda + C &= 0, \end{aligned}$$

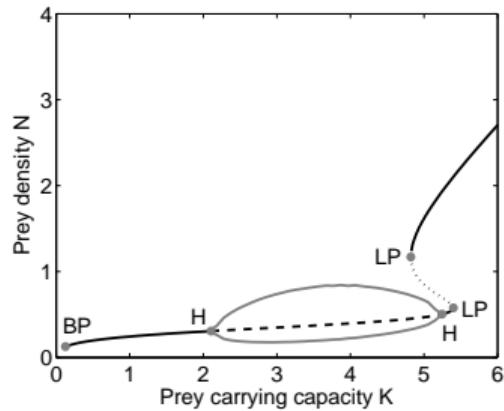
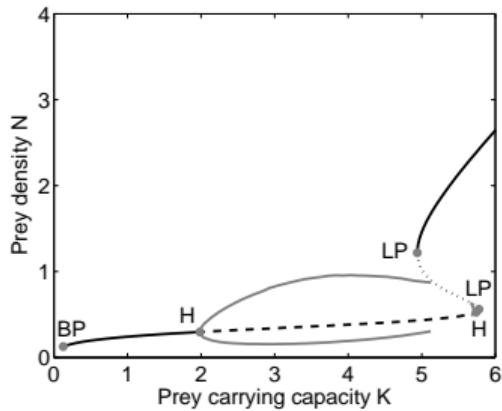
kde

$$\begin{aligned} \Lambda &= \lambda(P^*) , \\ C_1 &= \frac{er}{e-hm} , \\ C_2 &= \frac{m}{K(e-hm)} , \\ A &= K^2(e-hm)^2(rh - (e-hm)) , \\ B &= K(e-hm)(em - er - hm^2 - 3mhr) , \\ C &= 2mr(e+hm) > 0 . \end{aligned}$$

Bogdanova-Takensova bifurkace



Bogdanova-Takensova bifurkace



DĚKUJI ZA POZORNOST.